

§4.3 Frequent State Regeneration

- ◆ Many NVEs cannot afford the communications and processor overhead required to support absolute consistency through a centralized repository
- ◆ Many NVEs do not require high level consistency
- ◆ Limited and temporary error is allowable
- ◆ Smooth interface vs. absolute consistency
- ◆ Replace the distributed consistency protocol with a more aggressive state update notification system



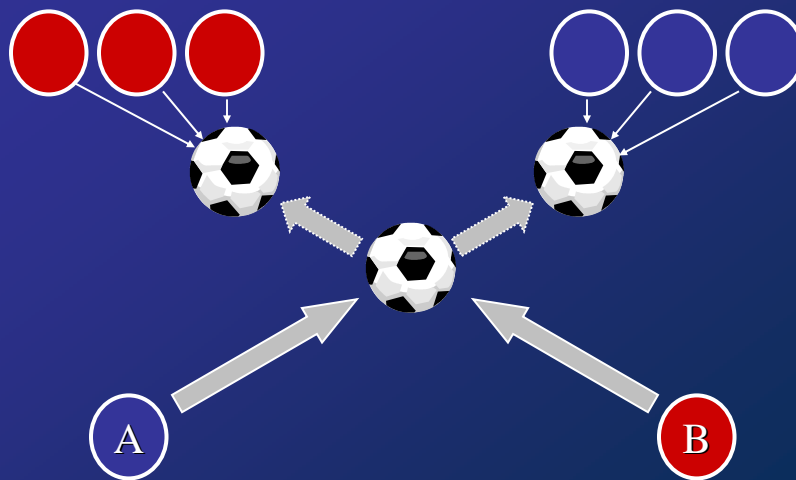
Frequent State Regeneration (cont'd)

- ◆ Source host does not care what state information is cached or available to other hosts
- ◆ Each update contains whole entity state, whether or not it has changed
- ◆ The owner of information uses *blind broadcast*
 - ❖ asynchronously and unreliably
 - ❖ at a regular interval
 - ❖ forward to all participants
- ◆ The receiver does not acknowledge packets
- ◆ Assumption: high transmission rate will make inconsistencies relatively unnoticeable
- ◆ Even with moderate packet loss, blind broadcast can typically deliver more packets than shared database due to its overhead

Entity Ownership: Background

- ◆ Blind broadcasting sacrifices absolute consistency, and reduces some flexibility that centralized repositories offer
- ◆ In a centralized repository system
 - ❖ any host can modify any entity
 - ❖ reliable and order-preserving updates
- ◆ With frequent state regeneration systems, ensure that multiple hosts do not attempt to update an entity at the same time

Problem: Who's Got the Ball Now? (Part II)

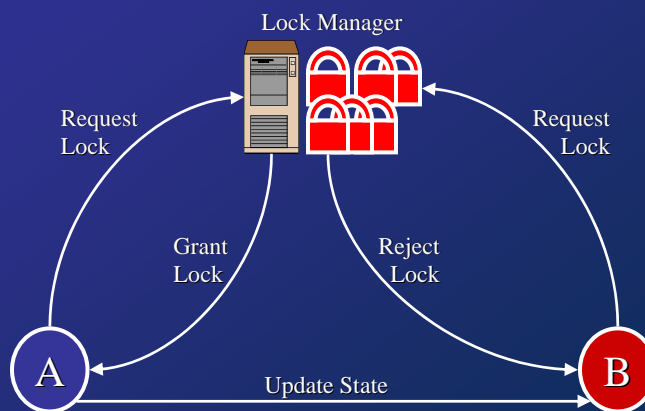


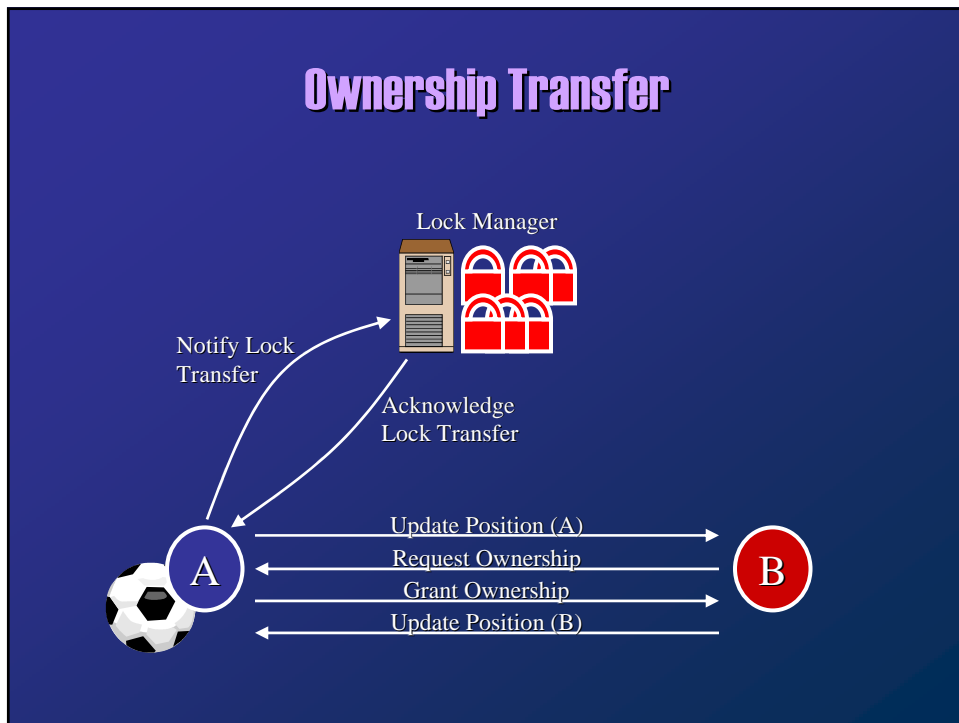
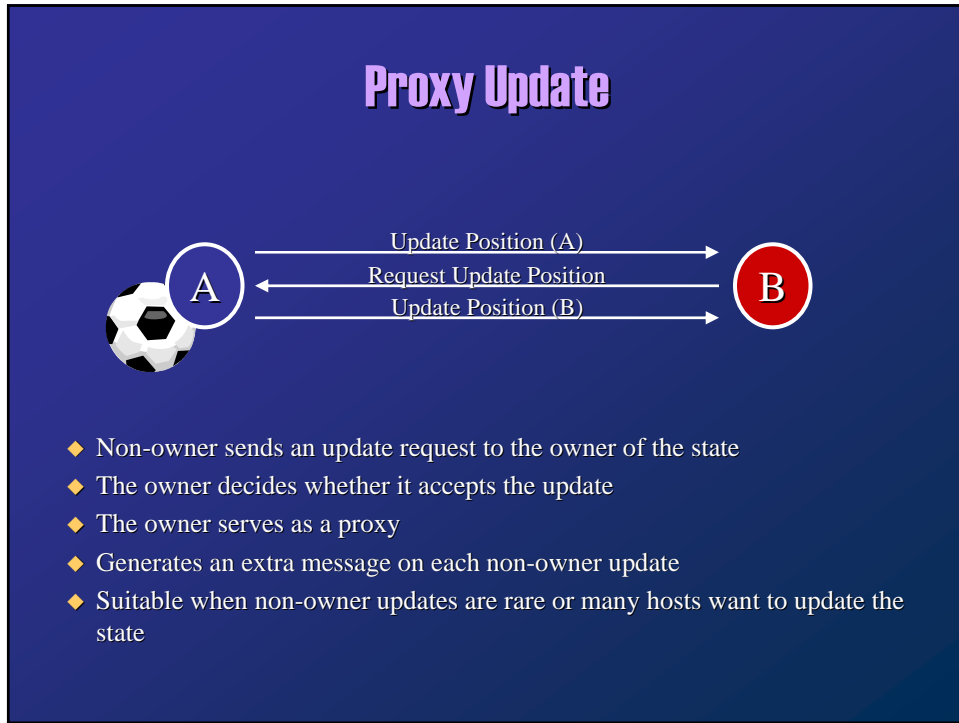
Explicit Entity Ownership

- ◆ Ensure that shared state can only be updated by one host at a time
 - ❖ exactly one host has the ownership of the state
 - ❖ the owner periodically broadcasts the value of the state
- ◆ Typically user's own representation (avatar) is owned by that user
- ◆ Locks on other entities are managed by a lock manager server
 - ❖ clients query to obtain ownership and contact to release it
 - ❖ the server ensures that each entity has only one owner
 - ❖ the server owns the entity if no one else does
 - ❖ failure recovery



Lock Manager: Example





Ownership Transfer (cont'd)

- ◆ The lock manager has the lock information at all times
- ◆ If the host fails, the lock manager defines the current lock ownership state

- ◆ Lock ownership transfer incurs extra message overhead
- ◆ Suitable when a single host is going to make a series of updates and there is little contention among hosts wishing to make updates

Reducing Broadcast Scope

- ◆ In a frequent state regeneration system, each host sends updates to all participants
 - ❖ causes hosts to receive lots of extraneous information
- ◆ Multicast and area-of-interest techniques
 - ❖ filter the updates before they get sent to inappropriate recipients
- ◆ Who should do the filtering?
 - ❖ the host itself?
 - ❖ a server?
- ◆ We shall return to this in §6



Frequent State Regeneration: Advantages and Drawbacks

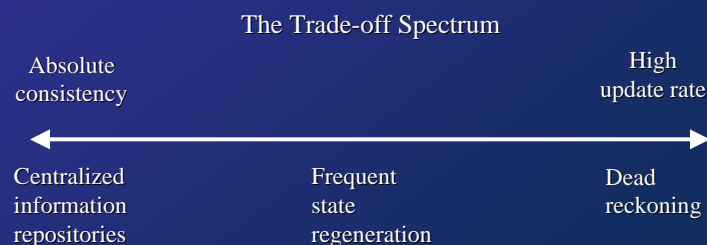
- ◆ Adds multi-user capabilities to existing single-user applications
- ◆ Blind broadcasting does not require a server, consistency protocol nor a lock manager (in most cases)
- ◆ Offers support for a large number of users
- ◆ Exhibits better interactive behaviour

- ◆ Requires considerable network bandwidth
- ◆ Susceptible to network latency
 - ❖ jitter = variation in network latency from one packet to the next
- ◆ Assumes that all hosts are broadcasting at the same rate

Flashback: Maintaining Dynamic Shared State

Three basic approaches to maintain dynamic shared state:

- ❖ shared repositories
- ❖ frequent broadcast
- ❖ state prediction

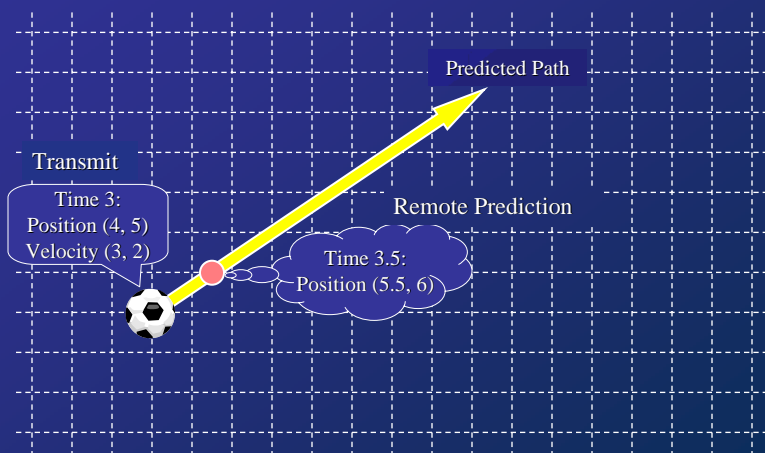


§4.4 Dead Reckoning of Shared State

- ◆ Transmit state update packets less frequently
- ◆ Use received information to *approximate* the true shared state
- ◆ In between updates, each host predicts the state of the entities



Dead Reckoning: Example

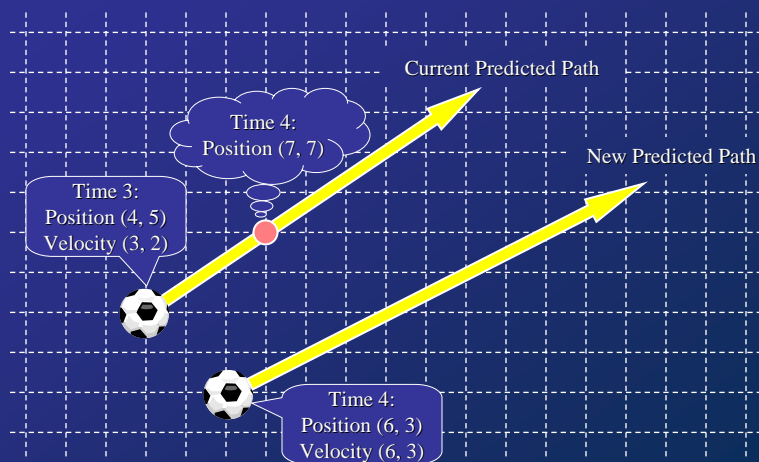


Dead Reckoning Protocol

DR protocol consists of two elements:

- ◆ prediction technique
 - ❖ how the entity's current state is computed based on previously received update packets
- ◆ convergence technique
 - ❖ how to correct the state information when an update is received

Prediction and Convergence



Prediction Using Derivative Polynomials

- ◆ The most common DR protocols use derivative polynomials
- ◆ Involves various derivatives of the entity's current position
- ◆ Derivatives of position
 1. velocity
 2. acceleration
 3. jerk

Zero-Order and First-Order Polynomials

- ◆ Zero-order polynomial
 - ❖ position p
 - ❖ the object's instantaneous position, no derivative information
 - ❖ predicted position after t seconds = p
- ⇒ The state regeneration technique
- ◆ First-order polynomial
 - ❖ velocity v
 - ❖ predicted position after t seconds = $vt + p$
 - ❖ update packet provides current position and velocity



Second-Order Polynomials

- ◆ We can usually obtain better prediction by incorporating more derivatives
- ◆ Second-order polynomial
 - ❖ acceleration a
 - ❖ predicted position after t seconds
 $= \frac{1}{2}at^2 + vt + p$
 - ❖ update packet: current position, velocity, and acceleration
 - ❖ popular and widely used
 - ❖ easy to understand and implement
 - ❖ fast to compute
 - ❖ relatively good predictions of position